

Measuring the Tendencies of CNNs to Learn Surface Level Regularities

J. Jo, Y. Bengio

Université de Montréal

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Reviewed by : Bill Zhang

University of Virginia

<https://qdata.github.io/deep2Read/>

Outline

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Summary

Introduction

Basic Premise and Motivation

- ▶ CNNs have achieved record-breaking object recognition on CIFAR-10, SVHN, and ImageNet datasets; de facto machine learning model for visual tasks
 - ▶ Good generalization Performance
- ▶ CNNs also sensitive to adversarial examples which humans can identify easily, but CNNs predict incorrectly usually with high confidence
 - ▶ Doubt that CNNs learn high-level abstraction; possibility that CNN overfits to superficial cues present in both training and testing sets

Introduction

Perturbation Map

- ▶ Create a perturbation map $F : X \rightarrow X'$ which satisfies the following:
 - ▶ Preserves object recognizability: For any $x \in X$ and its perturbation $x' \in X'$, recognizability should be preserved in human perspective
 - ▶ Qualitatively different image statistics: With property 1, guarantees preservation of high level abstraction but different superficial cues
 - ▶ Existence of non-trivial generalization gap: A model trained on unperturbed training set or perturbed training set tested on unperturbed and perturbed testing set should yield different accuracy results
- ▶ Use radial and random Fourier masks

Introduction

Claims

- ▶ Claim 1: CNNs are generalizing extremely well to an unseen test set
- ▶ Claim 2: General sensitivity to adversarial examples show that deep CNNs are not truly capturing abstractions in the dataset
- ▶ Hypothesis: The current incarnation of deep neural networks exhibit a tendency to learn surface statistical regularities as opposed to higher level abstractions in the dataset.
 - ▶ Sufficient for image recognition due to strong statistical properties of natural images, but only in a narrow distributional sense

Fourier Filtering

Overview and Equations

- ▶ Although natural images have high variance in pixel space, they tend to have most of their Fourier frequencies concentrated in low to mid-range frequencies
 - ▶ It is possible to filter frequencies out while preserving most of original image
- ▶ Consider the following sets:
 - ▶ (X, Y) , the original dataset
 - ▶ (X_{radial}, Y) , low frequency filtered version
 - ▶ (X_{random}, Y) , randomly filtered version
- ▶ With $X \in \mathbb{R}^{H \times W}$, the 2D DFT of an image is:

$$F(X)[k, l] := \frac{1}{\sqrt{HW}} \sum_{h=0}^{H-1} \sum_{w=0}^{W-1} X[w, h] e^{-j2\pi(\frac{wk}{W} + \frac{lh}{H})}$$

where k ranges from 0 to $W-1$ and l ranges from 0 to $H-1$

Fourier Filtering

Equations

- ▶ Consider a shifted DFT where DC component is in the center of the image; masks applied to all 3 color channels
- ▶ Radial Filtering: Parameterized by radius r , W and H even

$$M_r[i, j] := \begin{cases} 1 & \text{if } \|(i, j) - (W/2, H/2)\|_2 \leq r \\ 0 & \text{otherwise} \end{cases}$$

$$X_{radial} := F^{-1}(F(X) \circ M_r)$$

- ▶ Random Filtering: Parameterized by probability p

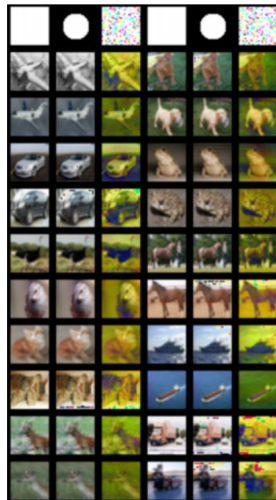
$$M_p[c, i, j] := \begin{cases} 0 & \text{with probability } p \\ 1 & \text{otherwise} \end{cases}$$

$$X_{random} := F^{-1}(F(X) \circ M_p)$$

Fourier Filtering

Post-Filtered Images

- ▶ Filtered images remain recognizable to humans; SVHN on left, CIFAR-10 on right



Experiments

Procedures

- ▶ Train on one of $(X_{train}^{unfiltered}, X_{train}^{radial}, X_{train}^{random})$ and test accuracy on all test sets $(X_{test}^{unfiltered}, X_{test}^{radial}, X_{test}^{random})$
- ▶ Define generalization gap as the maximum difference in accuracy among testing sets
- ▶ Used a Preact Resnet with Bottleneck architecture of depth 92 and 200
- ▶ Also trained on fully augmented training set

$$X_{train}^{augmented} := X_{train}^{unfiltered} \cup X_{train}^{radial} \cup X_{train}^{random}$$

Experiments

SVHN Results

- ▶ Train ResNet for 40 epochs using Nesterov Momentum; learning rate = 0.01, momentum = 0.9
- ▶ Batch size of 128; learning rate divided by 10 at epochs 20 and 30

| Train/Test | Unfilt. | Radial | Random | Gen. Gap |
|------------|---------|--------|--------|----------|
| Unfilt. | 1.95% | 8.41% | 2.68% | 6.46% |
| Radial | 3.50% | 5.07% | 5.67% | 2.17% |
| Random | 4.01% | 11.90% | 2.04% | 7.89% |
| Augmented | 2.11% | 5.06% | 2.15% | 2.95% |

(a) Preact-ResNet-Bottleneck-92 SVHN Generalization

| Train/Test | Unfilt. | Radial | Random | Gen. Gap |
|------------|---------|--------|--------|----------|
| Unfilt. | 1.88% | 8.31% | 2.42% | 6.43% |
| Radial | 3.56% | 4.90% | 4.77% | 1.34% |
| Random | 2.95% | 9.85% | 1.96% | 7.89% |
| Augmented | 1.94% | 4.87% | 2.06% | 2.93% |

(b) Preact-ResNet-Bottleneck-200 SVHN Generalization

Experiments

CIFAR-10 Results

- ▶ Train ResNet for 100 epochs using Nesterov Momentum; learning rate = 0.01 (boosted up to 0.1 after 400 updates), momentum = 0.9
- ▶ Batch size of 128; learning rate divided by 10 at epochs 50 and 75
- ▶ Augmented training for 120 epochs, decay at 60 and 80

| Train/Test | Unfilt. | Radial | Random | Gen. Gap |
|------------|---------|--------|--------|----------|
| Unfilt. | 5.54% | 25.75% | 12.31% | 20.21% |
| Radial | 6.91% | 7.91% | 18.45% | 11.54% |
| Random | 7.12% | 35.03% | 6.76% | 28.27% |
| Augmented | 5.85% | 7.89% | 6.74% | 2.04% |

(a) Preact-ResNet-Bottleneck-92 CIFAR-10 Generalization

| Train/Test | Unfilt. | Radial | Random | Gen. Gap |
|------------|---------|--------|--------|----------|
| Unfilt. | 5.22% | 23.37% | 11.26% | 18.15% |
| Radial | 6.35% | 7.07% | 17.09% | 10.74% |
| Random | 6.47% | 34.19% | 5.9% | 28.29% |
| Augmented | 5.37% | 7.25% | 6.3% | 1.88% |

(b) Preact-ResNet-Bottleneck-200 CIFAR-10 Generalization

Experiments

Discussion

- ▶ All trained models generalized well to unfiltered set; suggests that Fourier filtering produced datasets perceptually not far off from unfiltered sets
- ▶ Model trained on unfiltered set tend to latch onto image statistics of the training set, yielding a non-trivial generalization gap; no training set generalized to all other sets
- ▶ Although augmented set did reduce generalization gap, it does not mean augmented set is sufficient for all adversarial examples

Summary

- ▶ CNNs generalize well but are also sensitive to adversarial examples; models may be learning superficial cues rather than high-level abstraction
- ▶ Can use Fourier filtering as a perturbation map to show how models fail to recognize perceptually similar images due to different image statistics
- ▶ No training dataset generalized well to all of the datasets; model trained on augmented set, although effective at closing the generalization gap, may not be sensitive to other perturbation maps

References

- ▶ <https://arxiv.org/pdf/1711.11561.pdf>