

# Visual Feature Attribution using Wasserstein GANs

Christian F. Baumgartner<sup>1</sup>  
Ender Konukoglu<sup>1</sup>

Lisa M. Koch<sup>2</sup>    Kerem Can Tezcan<sup>1</sup>    Jia Xi Ang<sup>1</sup>  
for the Alzheimer's Disease Neuroimaging Initiative\*

<sup>1</sup>Computer Vision Lab, ETH Zurich

<sup>2</sup>Computer Vision and Geometry Group, ETH Zurich

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Presenter: Jack Lanchantin

# Visual Attribution Methods

- Most visual attribution methods training a classifier to predict the class and then use one of the following:
  - Saliency maps (gradient of class w.r.t image)
  - Activation maps (activations of the feature maps during classification)

# Visual Attribution Methods

- Shwartz-Ziv & Tishby showed that during training, NNs minimize the mutual information between input and output layers, thus compressing input features
  - The model may ignore features with low discriminative power if stronger features are available.
  - If there is evidence for a class at multiple locations in the image some locations may not influence the classification and may not be detected
- Training may be working in opposition to the goal of visual attribution

# This paper

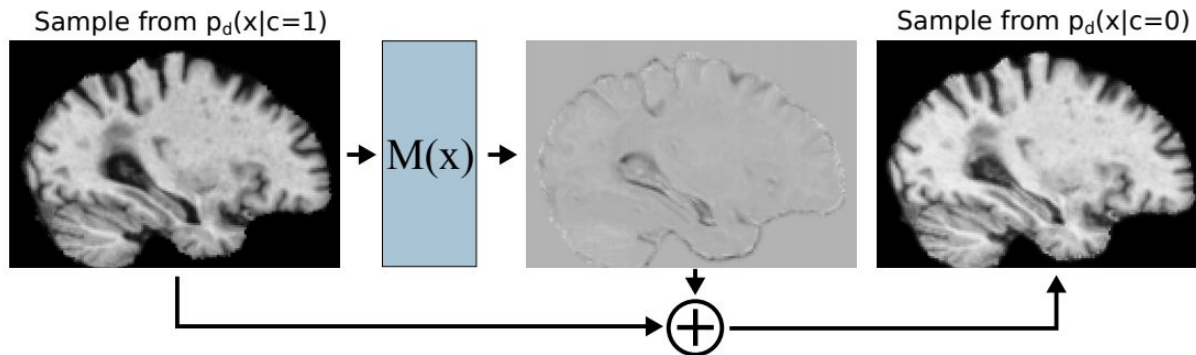
- Try to visualize evidence of a particular category in a way that captures all category-specific effects in an image.
- Find a map s.t. when added to image of one class, changes to another class
- 2 Differences between previous methods:
  - Does not rely on a classifier (assumes test image categories have already been determined)
  - Requires a baseline class (e.g. benign MRI image)

# Problem Formulation

- Given:
  - Classes  $c \in \{0, 1\}$ , a baseline class and a class of interest
  - Image  $x$
  - Distribution of images from class  $c = 0$  with  $p(x|c = 0)$
  - Distribution of images from class  $c = 1$  with  $p(x|c = 1)$

# Problem Formulation

Estimate a map function  $M(\cdot)$  that, when added to an image  $x_i$  from category  $c = 1$ , creates an image  $y_i = x_i + M(x_i)$  which is indistinguishable from the images sampled from  $p(x|c = 0)$ .



# Visual Attribution GAN (VAGAN)

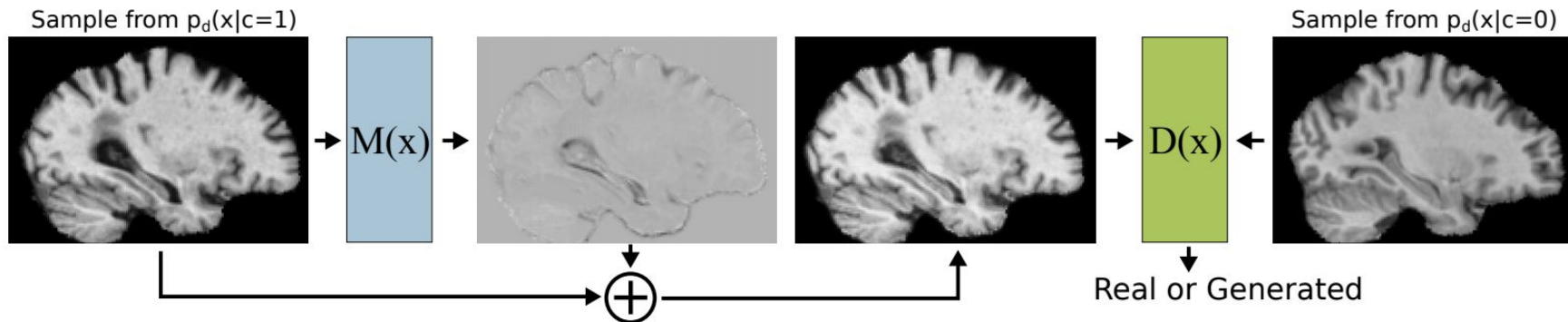


Figure 2. Overview of VA-GAN. During training images are sampled from the categories  $c \in \{0, 1\}$ . Images from  $c = 1$  are passed to the map generating function  $M(x)$ . The map generator aims to create additive maps which produce generated images that the critic  $D(x)$  cannot distinguish from images sampled from  $p_d(x|c = 0)$ . The critic,  $D(x)$  tries to assign different values to generated and real images. During testing,  $M(x)$  can be used directly to predict a map in a single forward pass.

# Visual Attribution GAN (VAGAN)

$$\mathcal{L}_{GAN}(M, D) = \mathbb{E}_{x \sim p_d(x|c=0)} [D(x)] \\ - \mathbb{E}_{x \sim p_d(x|c=1)} [D(x + M(x))].$$

$$\mathcal{L}_{reg}(M) = \|M(x)\|_1$$

$$M^* = \operatorname{argmin}_M \max_{D \in \mathcal{D}} \mathcal{L}_{GAN}(M, D) + \lambda \mathcal{L}_{reg}(M)$$

where  $\mathcal{D}$  is the set of 1-Lipschitz functions



# Baseline Approach - Additive Perturbation Maps

- Train a classifier  $f(x) = p(c = 1)$  and then optimize map  $m$  to lower  $p(c = 1)$ 
  - I.e. the image  $y_i = x_i + m$  should minimize  $f_i(y_i)$
  - Similar to VAGAN except that  $m$  is not a function of  $x_i$
- Finding image map  $m$  involves minimizing:

$$m^* = \underset{m}{\operatorname{argmin}} f(x_i + m) + \omega_1 \|m\|_1 + \omega_2 \sum_u \|\nabla m(u)\|_\beta^\beta.$$

where  $u$  are the pixels of  $m$

# Synthetic Data Experiments

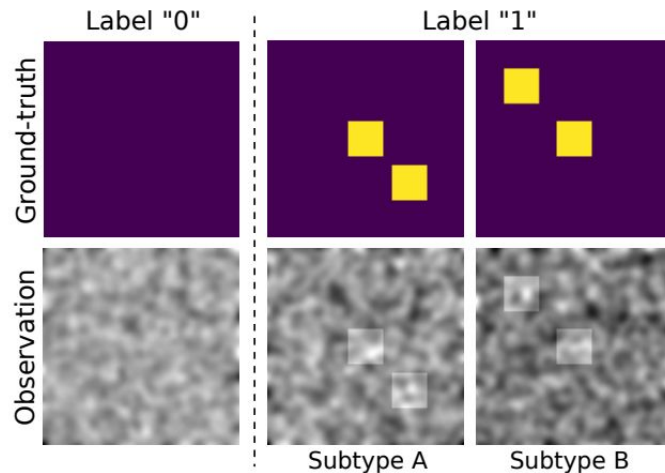


Figure 3. Description of synthetic data. We generated noisy observations from ground-truth effect maps. The dataset contained two categories: A baseline category 0 (e.g. healthy images) and category with an effect (e.g. patient images). The images in category 1 contained one of two subtypes, A or B, which is unknown to the algorithms. A: box in the lower right, B: box in the upper left.

# Synthetic Data Experiments

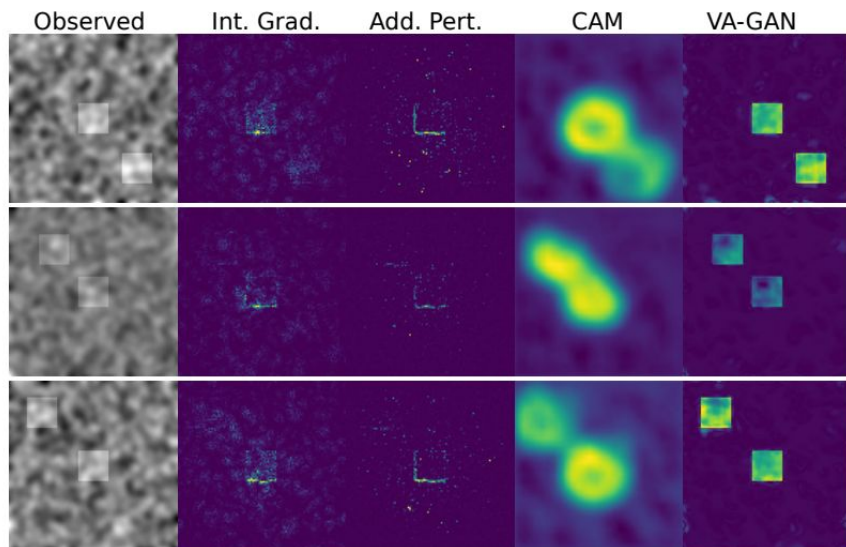


Figure 4. Examples of visual attribution on synthetic data obtained using the compared methods.

Table 1. NCC scores for experiments on synthetic data.

<b>Method</b>	<b>mean</b>	<b>std.</b>
Guided Backprop [55]	0.14	0.04
Integrated Gradients [56]	0.36	0.11
CAM [67]	0.48	0.04
Additive Perturbation	0.06	0.03
VA-GAN	<b>0.94</b>	0.07

# Experiments on real neuroimaging data

- Subjects who were diagnosed with MCI during a baseline examination but progressed to AD in one of the follow-up scans.
- We then aligned those images rigidly and subtracted them from each other to obtain an observed disease effect map.
- Training, validation, test: 825, 256, 207 samples

Table 2. NCC scores for experiments on neuroimaging data.

Method	mean	std.
Guided Backprop [55]	0.05	0.03
CAM [67]	0.09	0.07
Integrated Gradients [56]	0.13	0.05
Additive Perturbation	0.11	0.05
VA-GAN	<b>0.27</b>	0.15

