

Geometric Matrix Completion with Recurrent Multi-Graph Neural Networks

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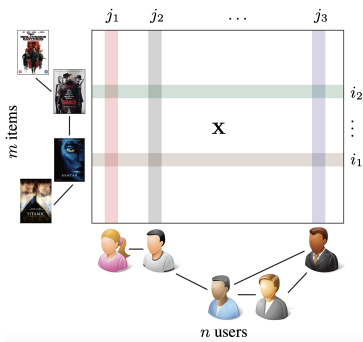
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<https://qdata.github.io/deep2Read>

Problem

- $X \in \mathbb{R}^{m \times n}$
- X_{ij} : the probability that USER j likes ITEM i
- Goal: reconstruct a huge X from a sparse set of known $\{X_{ij}\}$
- Example: Netflix challenge [8], 480k movies \times 18k users (8.5B entries), with only 0.011% known entries.



Previous effort 1: low rank assumption

- Key assumption: low rank (each entry is defined by a (USER, ITEM) pair, many entries share the same USER or ITEM)
- Challenge: NP-hard combinatorial problem
- Ω : known entries set

$$\min_{\mathbf{X}} \text{rank}(\mathbf{X}) \quad \text{s.t.} \quad x_{ij} = y_{ij}, \quad \forall ij \in \Omega, \quad (1)$$

Previous effort 2: convex solution

- Convex version
- $\|\cdot\|_*$: nuclear norm, L1-norm of the eigenvalue vector
- “Under some technical conditions” [1], (2) has the same solution as (1).

$$\min_{\mathbf{X}} \|\mathbf{X}\|_* + \frac{\mu}{2} \|\boldsymbol{\Omega} \circ (\mathbf{X} - \mathbf{Y})\|_{\text{F}}^2, \quad (2)$$

Previous effort 3: geometric method

- Model the relationship among the USERS
 - $\mathcal{G}_c = (\{1, \dots, n\}, \mathcal{E}_c, \mathbf{W}_c)$, \mathcal{E}_c : edge (relation) set.
 - $\mathbf{W}_c = (w_{ij}^c)$: *adjacency matrix*
 - $\mathbf{\Delta}_c = \mathbf{I} - \mathbf{D}^{-1/2}\mathbf{W}_c\mathbf{D}^{-1/2}$: graph Laplacian
 - $\|\mathbf{X}\|_{\mathcal{G}_c}^2 = \text{trace}(\mathbf{X}\mathbf{\Delta}_c\mathbf{X}^\top)$: *Dirichlet norm*
 - Both \mathbf{X} and $\mathbf{\Delta}_c\mathbf{X}^\top$ should be small.
- Model the relationship among the ITEMS
 - Similar $\mathcal{G}_r, \mathbf{W}_r, \mathcal{E}_r, \|\mathbf{X}\|_{\mathcal{G}_r}^2 = \text{trace}(\mathbf{X}^\top \mathbf{\Delta}_r \mathbf{X})$

$$\min_{\mathbf{X}} \|\mathbf{X}\|_{\mathcal{G}_r}^2 + \|\mathbf{X}\|_{\mathcal{G}_c}^2 + \frac{\mu}{2} \|\Omega \circ (\mathbf{X} - \mathbf{Y})\|_{\mathbb{F}}^2, \quad (3)$$

Previous effort 4: factorized models

- Explicitly model the low rank assumption by a factorized representation [12]
- $\mathbf{X} = \mathbf{WH}^\top$
- \mathbf{W}, \mathbf{H} are $m \times r$ and $n \times r$ matrices, $r \ll \min(m, n)$
- So, $\text{rank}(\mathbf{X}) \ll \min(m, n)$
- $\|\cdot\|_F^2$: Frobenius norm (L2-norm?)

$$\min_{\mathbf{W}, \mathbf{H}} \frac{1}{2} \|\mathbf{W}\|_F^2 + \frac{1}{2} \|\mathbf{H}\|_F^2 + \frac{\mu}{2} \|\Omega \circ (\mathbf{WH}^\top - \mathbf{Y})\|_F^2. \quad (4)$$

$$\min_{\mathbf{W}, \mathbf{H}} \frac{1}{2} \|\mathbf{W}\|_{\mathcal{G}_r}^2 + \frac{1}{2} \|\mathbf{H}\|_{\mathcal{G}_c}^2 + \frac{\mu}{2} \|\Omega \circ (\mathbf{WH}^\top - \mathbf{Y})\|_F^2. \quad (5)$$

Recall: spectral graph convolution

- (6): eigen decomposition of the graph Laplacian
- (7): spectral convolution between signal x and filter y
- (8): spectral convolution layer
 - Input $\mathbf{x} = \{\mathbf{x}_{l'}\} \in \mathbb{R}^{h \times w \times q'}$; Output $\tilde{\mathbf{x}} = \{\mathbf{x}_l\} \in \mathbb{R}^{h \times w \times q}$
- Drawbacks:
 - $O(n)$ parameters, no weight sharing
 - $O(n^2)$ computations (multiplication with Φ)

$$\Delta = \Phi \Lambda \Phi^T \quad (6)$$

$$\mathbf{x} \star \mathbf{y} = \Phi (\Phi^T \mathbf{x}) \circ (\Phi^T \mathbf{y}) = \Phi \text{diag}(\hat{y}_1, \dots, \hat{y}_n) \hat{\mathbf{x}} \quad (7)$$

$$\tilde{\mathbf{x}}_l = \xi \left(\sum_{l'=1}^{q'} \Phi \hat{Y}_{ll'} \Phi^T \mathbf{x}_{l'} \right), \quad l = 1, \dots, q \quad (8)$$

Recall: CNN on Graphs with Fast Localized Spectral Filtering [3]

- Chebyshev polynomial:
 $T_0(\lambda) = 1, T_1(\lambda) = \lambda, T_j(\lambda) = 2\lambda T_{j-1}(\lambda) - T_{j-2}(\lambda)$
- Rescaled graph Laplacian: $\tilde{\Delta} = 2\lambda_n^{-1} \Delta - \mathbf{I}$
- Rescaled eigen values: $\tilde{\Lambda} = 2\lambda_n^{-1} \Lambda - \mathbf{I}$
- Benefits:
 - $p = O(1)$ parameters
 - $O(n)$ computations (no multiplication with Φ)

$$\tilde{\mathbf{x}} = \tau_{\theta}(\tilde{\Delta})\mathbf{x} \quad (9)$$

$$\tau_{\theta}(\tilde{\Delta}) = \sum_{j=0}^{p-1} \theta_j \Phi T_j(\tilde{\Lambda}) \Phi^{\top} = \sum_{j=0}^{p-1} \theta_j T_j(\tilde{\Delta}) \quad (10)$$

Separable CNNs (sMGCNN)

If the factorized representation is used:

$$\tilde{\mathbf{w}}_l = \xi \left(\sum_{l'=1}^{q'} \sum_{j=0}^p \theta_{l',j}^r T_j(\tilde{\mathbf{\Delta}}_r) \mathbf{w}_{l'} \right) \quad (11)$$

$$\tilde{\mathbf{h}}_l = \xi \left(\sum_{l'=1}^{q'} \sum_{j'=0}^p \theta_{l',j'}^c T_{j'}(\tilde{\mathbf{\Delta}}_c) \mathbf{h}_{l'} \right) \quad (12)$$

Multi-Graph spectral convolution

$$\hat{\mathbf{X}} = \Phi_r^\top \mathbf{X} \Phi_c \quad (13)$$

$$\mathbf{X} \star \mathbf{Y} = \Phi_r (\hat{\mathbf{X}} \circ \hat{\mathbf{Y}}) \Phi_c^\top. \quad (14)$$

Localized version

$$\tilde{\mathbf{X}} = \sum_{j,j'=0}^p \theta_{jj'} T_j(\tilde{\mathbf{A}}_r) \mathbf{X} T_{j'}(\tilde{\mathbf{A}}_c) \quad (15)$$

- $(p + 1)^2 = O(1)$ parameters
- $O(mn)$ computations, linear complexity

Matrix diffusion with RNNs

Algorithm 1 (RMGCNN)

input $m \times n$ matrix $\mathbf{X}^{(0)}$ containing initial values

- 1: **for** $t = 0 : T$ **do**
 - 2: Apply the Multi-Graph CNN (13) on $\mathbf{X}^{(t)}$ producing an $m \times n \times q$ output $\tilde{\mathbf{X}}^{(t)}$.
 - 3: **for all elements** (i, j) **do**
 - 4: Apply RNN to q -dim $\tilde{\mathbf{x}}_{ij}^{(t)} = (\tilde{x}_{ij1}^{(t)}, \dots, \tilde{x}_{ijq}^{(t)})$ producing incremental update $dx_{ij}^{(t)}$
 - 5: **end for**
 - 6: Update $\mathbf{X}^{(t+1)} = \mathbf{X}^{(t)} + d\mathbf{X}^{(t)}$
 - 7: **end for**
-

Algorithm 2 (sRMGCNN)

input $m \times r$ factor $\mathbf{H}^{(0)}$ and $n \times r$ factor $\mathbf{W}^{(0)}$ representing the matrix $\mathbf{X}^{(0)}$

- 1: **for** $t = 0 : T$ **do**
 - 2: Apply the Graph CNN on $\mathbf{H}^{(t)}$ producing an $n \times q$ output $\tilde{\mathbf{H}}^{(t)}$.
 - 3: **for** $j = 1 : n$ **do**
 - 4: Apply RNN to q -dim $\tilde{\mathbf{h}}_j^{(t)} = (\tilde{h}_{j1}^{(t)}, \dots, \tilde{h}_{jq}^{(t)})$ producing incremental update $dh_j^{(t)}$
 - 5: **end for**
 - 6: Update $\mathbf{H}^{(t+1)} = \mathbf{H}^{(t)} + d\mathbf{H}^{(t)}$
 - 7: Repeat steps 2-6 for $\mathbf{W}^{(t+1)}$
 - 8: **end for**
-

(Separable) Recurrent Multi-Graph CNN

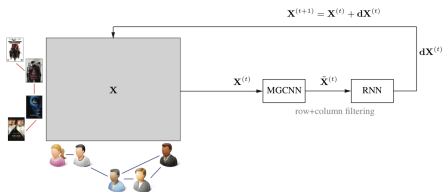


Figure: Recurrent MGCNN (RMGCNN)

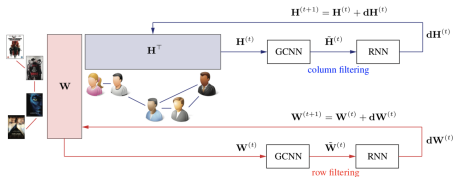


Figure: Separable Recurrent MGCNN (sRMGCNN)

Full matrix representation:

$$\ell(\Theta, \sigma) = \|\mathbf{X}_{\Theta, \sigma}^{(T)}\|_{\mathcal{G}_r}^2 + \|\mathbf{X}_{\Theta, \sigma}^{(T)}\|_{\mathcal{G}_c}^2 + \frac{\mu}{2} \|\Omega \circ (\mathbf{X}_{\Theta, \sigma}^{(T)} - \mathbf{Y})\|_{\mathbb{F}}^2. \quad (16)$$

Factorized representation:

$$\ell(\theta_r, \theta_c, \sigma) = \|\mathbf{W}_{\theta_r, \sigma}^{(T)}\|_{\mathcal{G}_r}^2 + \|\mathbf{H}_{\theta_c, \sigma}^{(T)}\|_{\mathcal{G}_c}^2 + \frac{\mu}{2} \|\Omega \circ (\mathbf{W}_{\theta_r, \sigma}^{(T)} (\mathbf{H}_{\theta_c, \sigma}^{(T)})^\top - \mathbf{Y})\|_{\mathbb{F}}^2.$$

Experiments

- $p = 4, T = 10, q = 32$
- Datasets:
 - Synthetic data [7]
 - MovieLens [10]
 - Flixster [6]
 - Douban [9]
 - YahooMusic [4]
- Baselines:
 - Classical Matrix Completion (MC) [2]
 - Inductive Matrix Completion (IMC) [5]
 - Geometric Matrix Completion (GMC) [7]
 - Graph Regularized Alternating Least Squares (GRALS) [11]

Synthetic data

Table: Comparison of different matrix completion methods using *users+items graphs* in terms of number of parameters (optimization variables) and computational complexity order (operations per iteration). Rightmost column shows the RMS error on Synthetic dataset.

METHOD	PARAMETERS	COMPLEXITY	RMSE
GMC	$O(mn)$	$O(mn)$	0.3693
GRALS	$O(m+n)$	$O(m+n)$	0.0114
RGCNN	$O(1)$	$O(mn)$	0.0053
sRGCNN	$O(1)$	$O(m+n)$	0.0106

Synthetic data

Table: Comparison of different matrix completion methods using *users graph only* in terms of number of parameters (optimization variables) and computational complexity order (operations per iteration). Rightmost column shows the RMS error on Synthetic dataset.

METHOD	PARAMETERS	COMPLEXITY	RMSE
GRALS	$O(m + n)$	$O(m + n)$	0.0452
sRGCNN	$O(m)$	$O(m + n)$	0.0362

Synthetic data

Table 3: Reconstruction errors for the synthetic dataset between multiple convolutional layers architectures and the proposed architecture. Chebyshev polynomials of order 4 have been used for both users and movies graphs (q' MGC q denotes a multi-graph convolutional layer with q' input features and q output features).

Method	Params	Architecture	RMSE
MGCNN _{3layers}	9K	1MGC32, 32MGC10, 10MGC1	0.0116
MGCNN _{4layers}	53K	1MGC32, 32MGC32 \times 2, 32MGC1	0.0073
MGCNN _{5layers}	78K	1MGC32, 32MGC32 \times 3, 32MGC1	0.0074
MGCNN _{6layers}	104K	1MGC32, 32MGC32 \times 4, 32MGC1	0.0064
RMGCNN	9K	1MGC32 + LSTM	0.0053

Table: Performance (RMS error) of different matrix completion methods on the MovieLens dataset.

METHOD	RMSE
GLOBAL MEAN	1.154
USER MEAN	1.063
MOVIE MEAN	1.033
MC [2]	0.973
IMC [5]	1.653
GMC [7]	0.996
GRALS [11]	0.945
sRGCNN	0.929

Table: Matrix completion results on several datasets (RMS error). For Douban and YahooMusic, a single graph (of users and items, respectively) was used. For Flixter, two settings are shown: users+items graphs / only users graph.

METHOD	FLIXSTER	DOUBAN	YAHOOMUSIC
GRALS	1.3126 / 1.2447	0.8326	38.0423
sRGCNN	1.1788 / 0.9258	0.8012	22.4149

Conclusion

- Application of [3] on Matrix Completion problems
- Open source
- Extensive experiments

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