Shapley Value Review

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- Divide some Value among members of a society
- A set of axioms about a fair distribution
- Shapley Vaue: A unique solution to satisfy all these 'fairness' axioms
- main idea: members should receive payments proportional to their 'marginal' contributions

- A Coalition Game of N players
- players: {1,..., N}
- Coalition $S \subseteq N$: subset of players
- The set of all players N: Grand Coalition
- A value/payoff function: A value $V(S): 2^N \to R$ for each coalition S

Shapley Value Review

- Assuming V(S) is superadditive : For all disjoint subsetd A,B $V(A \bigcup B) = V(A) + V(B)^{1}$
- how to divide the payoff or value among N?

¹no player has an incentive to play alone

Shapley value is the unique value that satisfies this:

- Efficiency: The sum of the Shapley values of all agents equals the value of the grand coalition, $\sum_{i=1}^{N} \psi_i(V) = V(N)$
- dummy player: *i* is a dummy player if the amount that *i* contributes to any coalition is exactly the amount that *i* is able to achieve alone. For any *V*, if *i* is a dummy player then ψ_i(*N*, *V*) = *V*({*i*})
- Symmetry: i and j are interchangeable if they always contribute the same amount to every coalition of the other agents. for all S that contains neither i nor j, V(S∪{i}) = V(S∪{j}).
- Additivity: For any two v_1 and v_2 , we have for any player *i* that $\psi_i(N, v_1 + v_2) = \psi_i(N, v_1) + \psi_i(N, v_2)$, where the game $(N, v_1 + v_2)$ is defined by $(v_1 + v_2)(S) = v_1(S) + v_2(S)$ for every coalition S.

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Shapley Value of feature i, for value function V:

$$\psi_i(V) = \frac{1}{N!} \sum_R V(P_i^R \bigcup\{i\}) - V(P_i^R)$$
(1)

R is the set of all permutations of N features, P_i^R the set of players in N which precede i in the order R

Shapley value, has a nice interpretation in terms of expected marginal contribution. It is calculated by considering all the possible orders of arrival of the players into a room and giving each player his marginal contribution. Say $v\{1\} = 10$, $v\{2\} = 12$, $v\{1,2\} = 23$. There are two possible orders of arrival: (1) first 1 then 2, and (2) first 2 then 1.

| Probability | Order of arrival | 1's marginal contribution | 2's marginal contribution |
|---------------|------------------|---------------------------|---------------------------|
| $\frac{1}{2}$ | first 1 then 2 | 10 | 13 |
| $\frac{1}{2}$ | first 2 then 1 | 11 | 12 |

Revised to account for repeated calculation of Shapley Value of feature i, for value function V:

$$\psi_i(V) = \frac{1}{N!} \sum_{S \subseteq N/\{i\}} (|S|!)(|N| - |S| - 1)! V(S \bigcup \{i\}) - V(S)$$
(2)

Example: Taxi Fare for three people

3 players share a taxi. Here are the costs for each individual journey: -Player 1: 6 - Player 2: 12 - Player 3: 42 How much should each individual contribute?



Figure 1: A taxi journey.

$$v(C) = \begin{cases} 6, & \text{if } C = \{1\} \\ 12, & \text{if } C = \{2\} \\ 42, & \text{if } C = \{3\} \\ 12, & \text{if } C = \{1,2\} \\ 42, & \text{if } C = \{1,3\} \\ 42, & \text{if } C = \{2,3\} \\ 42, & \text{if } C = \{1,2,3\} \end{cases}$$

calculate on board ²

²ANSWER: fair way of sharing the taxi fare is for player 1 to pay 2, player 2 to pay 5 and player 3 to pay 35

- Need V(S) for each subset
- usually defined as feature subset values form a coalition which causes a change in the classifier's prediction.
- retraining the classifier for each $S \subseteq N$, so the method would no longer be independent of the learning algorithm and we would also require the training set that the original classifier was trained on.

- Defining the value function V
- To be able to compute the Shapley for explanation, define the contribution function v(S) for a certain subset S.
- This function should resemble the value of f(x*) when we only know the value of the subset S of these features.
- use the expected output of the predictive model, conditional on the feature values $x_S = x_S^*$ of this subset:

$$v(\mathcal{S}) = \mathsf{E}[f(\mathbf{x})|\mathbf{x}_{\mathcal{S}} = \mathbf{x}_{\mathcal{S}}^*]. \tag{3}$$

or use a baseline value (all zeros or mean etc)

Shapley Value of each feature for an instance *x*:

$$\psi_i(V) = \frac{1}{N!|A|} \sum_R \sum_{y \in A} V(x, y, P_i^R \bigcup\{i\}) - V(x, y, P_i^R)$$
(4)

• Sample over all permutations and feature values(discrete case): $O(2^N|A|)$, where N is the number of features and |A| is the possible values of features in total set A(exponential again)

- sampling
- kernelSHAP
- L Shapley C shapley
- Most can't work on image/sequence data with too many features

$$f(\mathbf{x}^*) = \phi_0 + \sum_{j=1}^M \phi_j^*,$$

where $\phi_0 = \mathsf{E}[f(\mathbf{x})]$ and ϕ_j^* is the ϕ_j for the prediction $\mathbf{x} = \mathbf{x}^*$. That is, the Shapley values explain the difference between the prediction $y^* = f(\mathbf{x}^*)$ and the global average prediction. In its simplest form, the WLS problem can be stated as the problem of minimizing

$$\sum_{\mathcal{S}\subseteq\mathcal{M}} (v(\mathcal{S}) - (\phi_0 + \sum_{j\in\mathcal{S}} \phi_j))^2 k(M,\mathcal{S}),$$
(5)

with respect to ϕ_0, \ldots, ϕ_M , where $k(M, S) = (M-1)/(\binom{M}{|S|}|S|(M-|S|))$, are denoted the Shapley kernel weights.

KernelSHAP

Then (5) may be rewritten to

$$(\mathbf{v} - \mathbf{Z}\phi)^T \mathbf{W}(\mathbf{v} - \mathbf{Z}\phi),$$
 (6)

for which the solution is

$$\phi = \left(\boldsymbol{Z}^{\mathsf{T}} \boldsymbol{W} \boldsymbol{Z} \right)^{-1} \boldsymbol{Z}^{\mathsf{T}} \boldsymbol{W} \boldsymbol{v}.$$
(7)

- Z: 2^M × (M + 1) binary matrix representing all possible combinations of inclusion/exclusion of the M features³
- \boldsymbol{v} : vector containing $v(\mathcal{S})$,
- \boldsymbol{W} : $2^M \times 2^M$ diagonal matrix containing $k(M, |\mathcal{S}|)$, ⁴

³where the first column is 1 for every row, while entry j + 1 of row *l* is 1 if feature *j* is included in combination *l*, and 0 otherwise.

⁴where S in both cases resembles the feature combinations of the corresponding row in Z.

- When the model contains more than a few features *M*, computing the rhs : computationally expensive.
- The Shapley kernel weights have very different sizes, meaning that the majority of the subsets S, that is, the rows in Z, contributes very little to the Shapley value.
- Hence, assuming that we have an proper approximation for the elements in v, a consistent approximation may be obtained by sampling (with replacement) a subset D of M from a probability distribution following the Shapley weighting kernel, and using only those rows Z_D of Z and elements v_D of v in the computation. As the Shapley kernel weights are used in the sampling, the sampled subsets are weighted equally in the new least squares problem.

- Do away with all possible feature values: use some reference x₀
- Choose 'good' subsets based on graph structure
- LShapley:

$$\hat{\phi}_{x}^{k}(i) = \frac{1}{|\mathcal{N}ki|} \sum_{\substack{T \ni i \\ T \subseteq \mathcal{N}ki}} \frac{1}{\binom{|\mathcal{N}ki|-1}{|\mathcal{T}|-1}} m_{x}(\mathcal{T}, i).$$
(8)

CShapley:

$$\tilde{\phi}_{x}^{k}(i) = \sum_{U \in \mathcal{C}_{k}(i)} \frac{2}{(|U|+2)(|U|+1)|U|} m_{x}(U,i),$$
(9)

f denotes the function that maps an input sentence $x = (x_1, \ldots, x_d)$ to the log probability score of a selected class.

Let $2^{[d]}$ denote the powerset of $[d] := \{1, 2, \ldots, d\}$. The parse tree maps the sentence to a collection of subsets, denoted as $\mathcal{P}t \subset 2^{[d]}$, where each subset $S \in \mathcal{P}$ contains the indices of words corresponding to one node in the parse tree.

$$\min_{\psi \in \mathbb{R}^d} \sum_{S \in \mathcal{P}} [v(S) - \sum_{i \in S} \psi_i]^2,$$
(10)

where component ψ_i of the optimal ψ is the importance score of word with index *i*.

Data Shapley[GZ19]

Algorithm 1 Truncated Monte Carlo Shapley

Input: Train data $D = \{1, ..., n\}$, learning algorithm \mathscr{A} , performance score V **Output:** Shapley value of training points: ϕ_1, \ldots, ϕ_n Initialize $\phi_i = 0$ for i = 1, ..., n and t = 0while Convergence criteria not met do $t \leftarrow t + 1$ π^t : Random permutation of train data points $v_0^t \leftarrow V(\emptyset, \mathscr{A})$ for $j \in \{1, ..., n\}$ do if $|V(D) - v_{i-1}^t|$ < Performance Tolerance then $v_{i}^{t} = v_{i-1}^{t}$ else $v_j^t \leftarrow V(\{\pi^t[1],\ldots,\pi^t[j]\},\mathscr{A})$ end if $\phi_{\pi^{t}[i]} \leftarrow \frac{t-1}{t} \phi_{\pi^{t-1}[i]} + \frac{1}{t} (v_{i}^{t} - v_{i-1}^{t})$ end for end while

- takes into account which algorithm came first
- Paper Quantifying Algorithmic Improvements over Time [KFM⁺18]

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